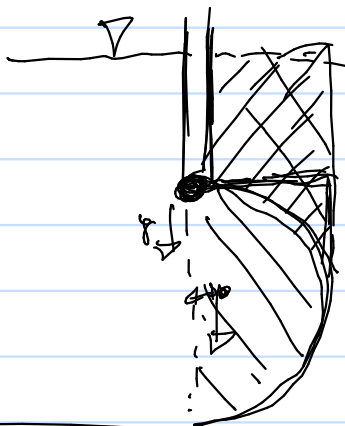


$$F_{OS} = \int_0^{2R} \gamma (h+R) 2R b \quad (\text{VERSO DESTRA})$$

$$F_{VS} = \int_0^{2R} \gamma \frac{R^2}{2} b \quad (\text{VERSO IL BASSO})$$



MEGLIORANDO LA FORZA
 RISULTANTE NEL CENTRO
 DELLA CIRCONFERENZA

$$M_o = \int_0^{2R} \gamma (h+R) 2R^2 b$$

OPPURE

$$\begin{aligned} F_{OS} &= \int_0^{2R} \gamma (h+y) b dy \\ &= \gamma \gamma b \left[hy + \frac{y^2}{2} \right]_0^{2R} \\ &= \gamma \gamma b \left(h 2R + \frac{4R^2}{2} \right) \\ &= \gamma \gamma b (h+R) 2R b \end{aligned}$$

$$\begin{aligned} M_{OS} &= \int_0^{2R} \gamma (h+y) \gamma b dy \\ &= \gamma \gamma b \left[h \frac{y^2}{2} + \frac{y^3}{3} \right]_0^{2R} \\ &= \gamma \gamma b \left(h \frac{4R^2}{2} + \frac{8R^3}{3} \right) \\ &= \gamma \gamma b 2R^2 \left(h + \frac{4R}{3} \right) \end{aligned}$$

$$M_{or} = \rho g \frac{\pi R^2}{2} b \frac{4}{3} R$$

$$= \rho g \frac{2}{3} R^3 b$$

$$M_D = M_{os} + M_{or} = \rho g b 2R^2 \left(h + \frac{4}{3}R - \frac{1}{3}R \right)$$
$$= \rho g b 2R^2 (h + R)$$

$$F_{ob} = \rho g R (2Rb) = \rho g 2R^2 b \quad (\text{USANDO SINUSOIDA})$$

$$F_{vd} = \rho g b \left(R^2 + \frac{\pi R^2}{4} \right) \quad (\text{USANDO L'ALTRA})$$

$$M_{ob} = -\rho g 2R^2 b \frac{2}{3} 2R = -\frac{8}{3} \rho g R^3 b$$

$$M_{vd} = \rho g b \left(R^2 \frac{R}{2} + \frac{\pi R^2}{4} \frac{4}{3} R \right)$$

$$M_D = \rho g b \left(\frac{R^3}{2} + \frac{R^3}{3} - \frac{8}{3} R^3 \right)$$

$$= \rho g b \left(\frac{R^3}{2} - \frac{7}{3} R^3 \right)$$

$$= \rho g b \left(\frac{3R^3 - 14R^3}{6} \right) = -\rho g b \frac{11}{6} R^3$$

OPPURE (SPEZZANDO IN TRE)

$$F_{0D}^1 = \cancel{S_0} \frac{R}{2} R b$$

$$M_{0D}^1 = \cancel{S_0} \frac{R}{2} R b \frac{2}{3} R = -\cancel{S_0} \frac{R^3}{3} b$$

$$M_{VD} = 0$$

$$F_{0D}^2 = \cancel{S_0} \left(R + \frac{R}{2}\right) R b$$

$$M_{0D}^2 = \cancel{S_0} \left(\frac{3}{2} R\right) R b R = -\cancel{S_0} \frac{3}{2} R^3 b$$

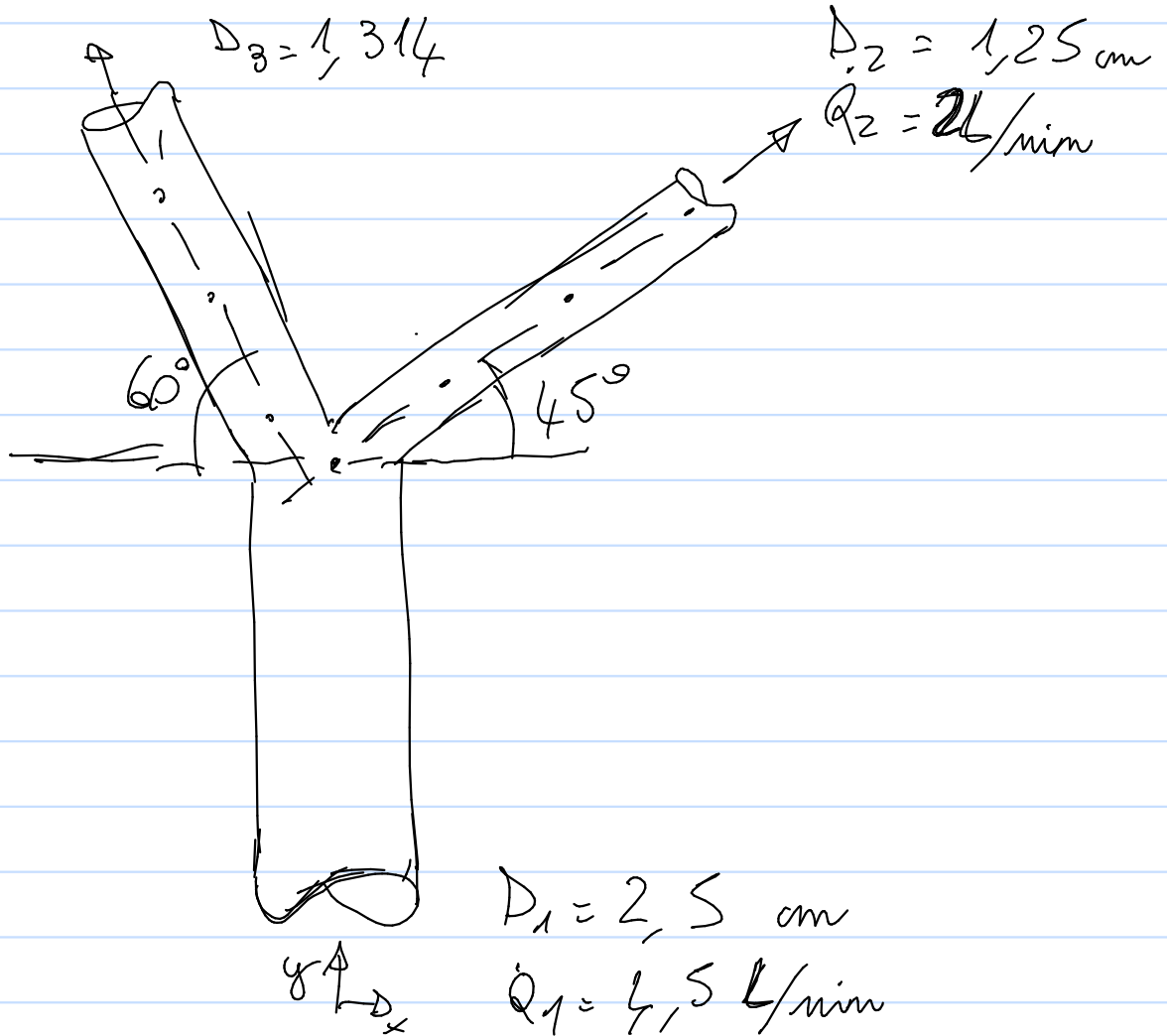
$$\begin{aligned} M_D &= -\cancel{S_0} b R^3 \left(\frac{3}{2} + \frac{1}{3}\right) = -\cancel{S_0} b R^3 \left(\frac{9+2}{6}\right) \\ &= -\cancel{S_0} b R^3 \left(\frac{11}{6}\right) \end{aligned}$$

$$M_S + M_D = 0$$

$$\cancel{S_0} b (h+R) 2R^2 b - \cancel{S_0} \cancel{S_0} b R^3 \frac{11}{6} = 0$$

$$\frac{S_S}{S_D} = \frac{11}{12} \frac{R}{h+R}$$

$$\rho = 1060 \text{ g/cm}^3$$



ONS MASSA

$$\rho U_1 A_1 = \rho U_2 A_2 + \rho U_3 A_3$$

$$\dot{Q}_1 = \dot{Q}_2 + \dot{Q}_3$$

$$Q_3 = 2,5 \text{ L/min}$$

$$U_1 = \frac{Q_1}{A_1} = \frac{Q_1}{\frac{\pi D_1^2}{4}} = \frac{4500 \text{ cm}^3/\text{min} \cdot \frac{1 \text{ min}}{60 \text{ sec}}}{\frac{\pi \cdot 2,5^2 \text{ cm}^2}{4}}$$

$$= 25,28 \text{ cm/s}$$

$$U_2 = 27,16 \text{ cm/s}$$

$$U_3 = 30,42 \text{ cm/s}$$

cons pDM y

$$\int_{A_1} \rho \vec{U}_1 \cdot \vec{n}_1 dA + \int_{A_2} \rho \vec{U}_2 \cdot \vec{n}_2 dA + \int_{A_3} \rho \vec{U}_3 \cdot \vec{n}_3 dA$$

$$= \int_{A_1} P_1 \vec{n}_1 \cdot \vec{z} dA - \int_{A_2} P_2 \vec{n}_2 \cdot \vec{z} dA - \int_{A_3} P_3 \vec{n}_3 \cdot \vec{z} dA + F_y$$

$$\rho U_1 (-U_1) A_1 + \rho U_2 \cos 45 U_2 A_2 + \rho U_3 \cos 30 U_3 A_3$$

$$= + P_1 A_1 - P_2 A_2 \cos 45 - P_3 \cos 30 A_3 + F_y$$

$$- \rho U_1^2 A_1 + \rho U_2^2 A_2 \cos 45 + \rho U_3^2 A_3 \cos 30$$

$$- P_1 A_1 + P_2 A_2 \cos 45 + P_3 A_3 \cos 30 = F_y$$

$$\frac{U_1^2}{2} + \cancel{\frac{P_1}{\rho}} = \frac{U_2^2}{2} + \cancel{\frac{P_2}{\rho}}$$

$$P_2 = P_1 + \frac{\rho}{2} (U_1^2 - U_2^2)$$

$$= 186651 \frac{\rho}{\text{cm}^2 \text{s}^2} - 267,22 \frac{\rho}{\text{cm}^2 \text{s}^2}$$

$$= 186383,8 \frac{\rho}{\text{cm}^2 \text{s}^2}$$

$$P_3 = P_1 + \frac{\rho}{2} (U_1^2 - U_3^2) = 186274,6 \frac{\rho}{\text{cm}^2 \text{s}^2}$$

$$F_y = - 535089 \frac{\text{g cm}}{\text{s}^2}$$

LA FORZA ESERCITATA DAL
FLUIDO SULLA BIFURCAZIONE
HA SEGNO OPPOSTO (VERSO
L'ALTO)

$$535089 \frac{\text{g cm}}{\text{s}^2} \quad \text{e} \quad 5 \frac{\text{kg m}}{\text{s}^2}$$

VALVOLE A SARACINESCA

$$\Delta P = f(h, d, v, \rho, \mu)$$

$$[\Delta P] = \frac{N}{m^2} = \frac{\frac{kg}{m}}{s^2 m^2} = \frac{kg}{m s^2}$$

$$[h, d] = m$$

$$[v] = m/s$$

$$[\rho] = kg/m^3$$

$$[\mu] = [\rho v d] = \frac{kg}{m^3} \frac{m}{s} m = \frac{kg}{m s}$$

6 VAR \Rightarrow 3 GRUPPI
3 DIM

VAR RIPETUTE v, ρ, d

COMBINANDO 1) $\rho, v, d, \Delta P \Rightarrow \frac{\Delta P}{\rho v^2} = F_u$

2) $\rho, v, d, \mu \Rightarrow \frac{\rho v d}{\mu} = Re$

3) $\rho, v, d, h \Rightarrow \frac{h}{d}$

$$h_m = \frac{1}{8} h_p$$

$$d_m = \frac{1}{8} d_p$$

$$\frac{h_m}{d_m} = \frac{h_p}{d_p} \quad \left(\begin{array}{l} \text{SIMILITUDINE} \\ \text{GEOMETRICA} \end{array} \right)$$

$$V_m \quad \text{QUANDO} \quad V_p = 3 \text{ m/s}$$

$$Re_m = Re_p$$

$$\frac{\rho_m V_m d_m}{\mu_m} = \frac{\rho_p V_p d_p}{\mu_p}$$

$$V_m = \frac{\rho_p}{\rho_m} \frac{d_p}{d_m} \frac{\mu_m}{\mu_p} V_p$$

$$= \frac{800}{1000} \cdot 8 \cdot \frac{0,001}{0,002} V_p$$

$$= \frac{4^2}{8} \cdot 8 \cdot \frac{1}{2} V_p = 6 \text{ m/s}$$

ΣΟΜΑΤΙΑ ΠΡΟΣΑΡΤΗ

$$U = x^2 - y^2 + x$$

$$v = -2xy - y$$

$$\nabla \cdot \vec{v} = 2x + 1 - 2x - 1 = 0$$

ΑΚΕΣΑΖΙΟΝ ΠΥΚΝΩΣΗ (2,1)

$$Q = \frac{DQ}{Dt} = \frac{\partial U}{\partial t} + \vec{v} \cdot \nabla U$$

$$\nabla U = \begin{bmatrix} 2x+1 & -2y \\ -2y & -2x-1 \end{bmatrix}$$

$$\vec{v} \cdot \nabla U = \begin{bmatrix} (x^2 - y^2 + x)(2x+1) + (-2xy - y)(-2y) \\ (x^2 - y^2 + x)(-2y) + (-2xy - y)(-2x-1) \end{bmatrix}$$

$$W(2,1) Q = 35 \hat{i} + 15 \hat{j}$$

$$\vec{f} = \mu (\sigma_0 + \sigma_0)^2$$

$$\mu = 1$$

$$\vec{f} = 2 \begin{bmatrix} 2x+1 & -2y \\ -2y & -2x-1 \end{bmatrix}$$

SFORZO SUPERFICIE NORMALE \vec{f}

$$\vec{F} = \vec{f} \cdot \vec{n}_0 = \vec{f} \cdot \vec{S} = \begin{bmatrix} -4y & -4x-2 \end{bmatrix}$$